Coupled Systems of Differential Equations

DANCE Winter School Pamplona January 27, 2012

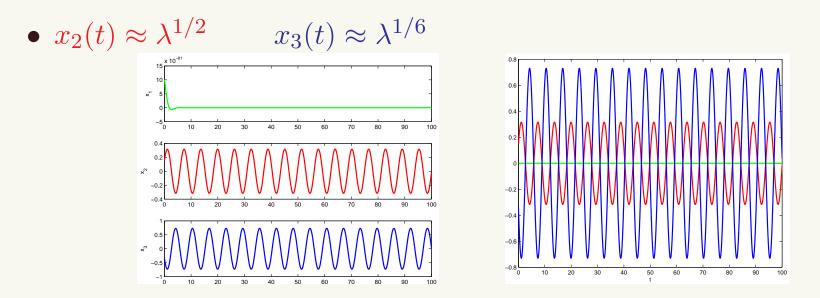
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Outine

- Why $\frac{1}{6}$?
- Feedforward network as a motif
- Heteroclinic cycles in networks
- A model for rivalry

Three-Cell Feed-Forward Network

• Network supports solution by Hopf bifurcation where $x_1(t)$ equilibrium $x_2(t), x_3(t)$ time periodic



G., Nicol, and Stewart (2004); Elmhirst and G. (2005); G. and Postlethwaite (2012)

F.F. Ex. $f(u,v) = (\lambda + i - |u|^2)u - v$ where $u, v \in \mathbf{C}$

$$\dot{x}_1 = f(x_1, x_1) = (\lambda + i - |x_1|^2)x_1 - x_1$$

 $x_1 = 0$ is a stable equilibrium for $\lambda < 1$

$$\dot{x}_2 = f(x_2, x_1) = (\lambda + i - |x_2|^2)x_2 - x_1$$

$$\dot{x}_2 = f(x_2, 0) = (\lambda + i - |x_2|^2)x_2$$

 $x_2(t) = \sqrt{\lambda}e^{it}$ is stable periodic solution for $0 < \lambda < 1$

$$\dot{x}_3 = f(x_3, x_2) = (\lambda + i - |x_3|^2)x_3 - x_2$$

$$\dot{x}_3 = f(x_3, \sqrt{\lambda}e^{it}) = (\lambda + i - |x_3|^2)x_3 - \sqrt{\lambda}e^{it}$$

F.F. Ex.
$$f(u, v) = (\lambda + i - |u|^2)u - v$$

 $x_1 = 0$ is a stable equilibrium for $\lambda < 1$ $x_2(t) = \sqrt{\lambda}e^{it}$ is stable periodic solution for $0 < \lambda < 1$

$$\dot{x}_3 = (\lambda + i - |x_3|^2)x_3 - \sqrt{\lambda}e^{it}$$

Set $x_3(t) = y(t)e^{it}$

$$\dot{y}e^{it} + yie^{it} = (\lambda + i - |y|^2)ye^{it} - \sqrt{\lambda}e^{it}$$

$$\dot{y}e^{it} + \boxed{yie^{it}} = (\lambda + \boxed{i} - |y|^2) \boxed{ye^{it}} - \sqrt{\lambda}e^{it}$$
$$\dot{y}e^{it} = (\lambda - |y|^2)ye^{it} - \sqrt{\lambda}e^{it}$$
$$\dot{y}\boxed{e^{it}} = (\lambda - |y|^2)y\boxed{e^{it}} - \sqrt{\lambda}\boxed{e^{it}}$$

$$\dot{y} = (\lambda - |y|^2)y - \sqrt{\lambda}$$

F.F. Ex.
$$f(u, v) = (\lambda + i - |u|^2)u - v$$

 $x_1 = 0$ is a stable equilibrium for $\lambda < 1$ $x_2(t) = \sqrt{\lambda}e^{it}$ is stable periodic solution for $0 < \lambda < 1$ $x_3(t) = y(t)e^{it}$

$$\dot{y} = (\lambda - |y|^2)y - \sqrt{\lambda}$$

Set $y(t) = \lambda^{1/6} u(t)$

$$\lambda^{1/6} \dot{u} = (\lambda^{7/6} - \lambda^{3/6} |u|^2)u - \lambda^{3/6}$$

$$\dot{u} = (\lambda - \lambda^{1/3} |u|^2) u - \lambda^{1/3}$$

$$\dot{u} = -\lambda^{1/3}(|u|^2u + 1) + \lambda u$$

F.F. Ex.
$$f(u, v) = (\lambda + i - |u|^2)u - v$$

$$\begin{split} x_1 &= 0 \text{ is a stable equilibrium for } \lambda < 1 \\ x_2(t) &= \sqrt{\lambda} e^{it} \text{ is stable periodic solution for } 0 < \lambda < 1 \\ x_3(t) &= y(t) e^{it} \\ y(t) &= \lambda^{1/6} u(t) \end{split}$$

$$\dot{u} = -\lambda^{1/3}(|u|^2u + 1) + \lambda u$$

Solve $\dot{u} = 0$ for equilibria

$$-(|u|^2u+1) + \lambda^{2/3}u = 0$$

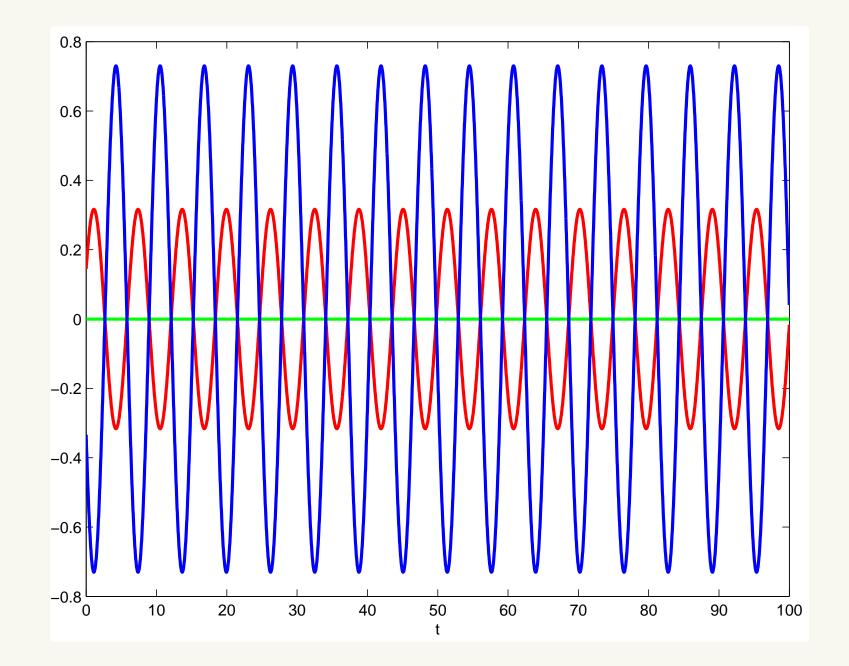
Use IFT to obtain branch of (stable) equilibria

$$u_0(\lambda) = -1 + O(\lambda^{2/3})$$

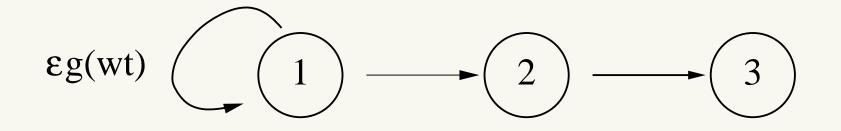
Thus $x_3(t)$ is periodic with same period as $x_2(t)$

$$x_3(t) = y(t)e^{it} = \lambda^{1/6}u(t)e^{it} \to \lambda^{1/6}u_0(\lambda)e^{it} = -\frac{\lambda^{1/6}e^{it}}{\lambda^{1/6}e^{it}} + O(\lambda^{5/6})$$

Feed Forward Simulation



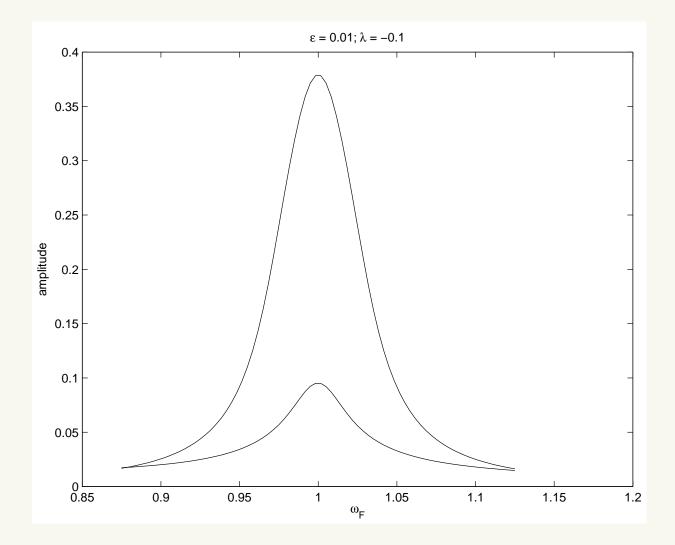
Forced Feed Forward Network



- forcing at frequency ω_f and amplitude ε
- network tuned near Hopf bifurcation with frequency ω_h
- $\lambda < 0$ so that equilibrium is stable
- Three parameters: λ , ϵ , $\omega_f \omega_h$

Numerics with Aronson

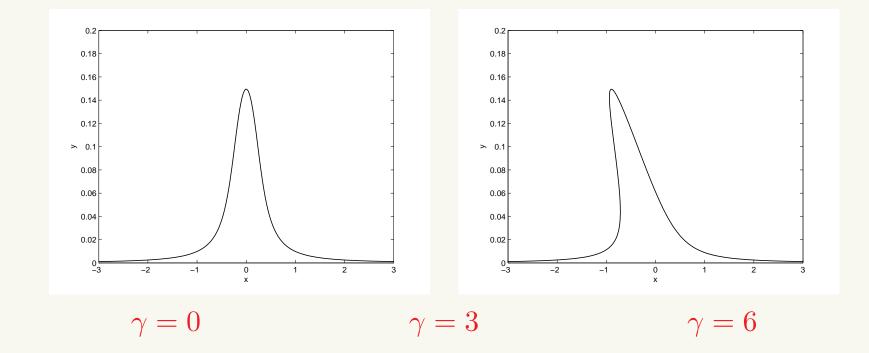
• $\dot{z} = (-0.1 + i - |z|^2)z + 0.01(e^{i\omega_F t} + 2e^{2i\omega_F t} - 0.5e^{3i\omega_F t})$



Periodic Forcing of Hopf

•
$$\dot{z} = (\lambda + \omega_H i - (1 + i\gamma)|z|^2)z + \varepsilon e^{2\pi i \omega_f t}$$

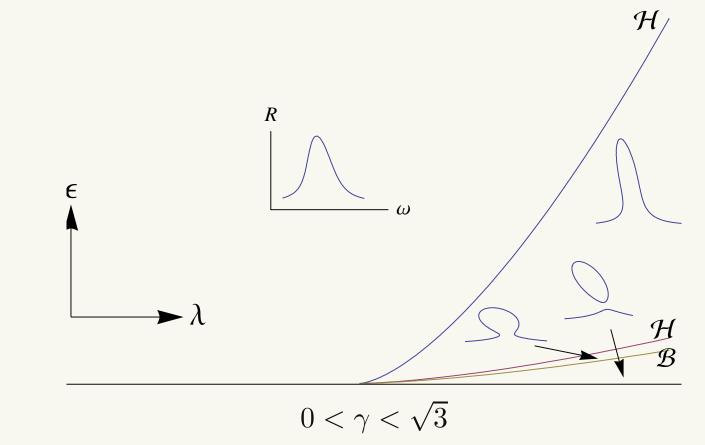
•
$$\omega = \omega_f - \omega_H$$
, $\lambda = -0.0218$, $\varepsilon = 0.02$



G., Postlethwaite, Shiau, and Zhang (2009)

Bifurcation Diagrams: $\gamma < \sqrt{3}$

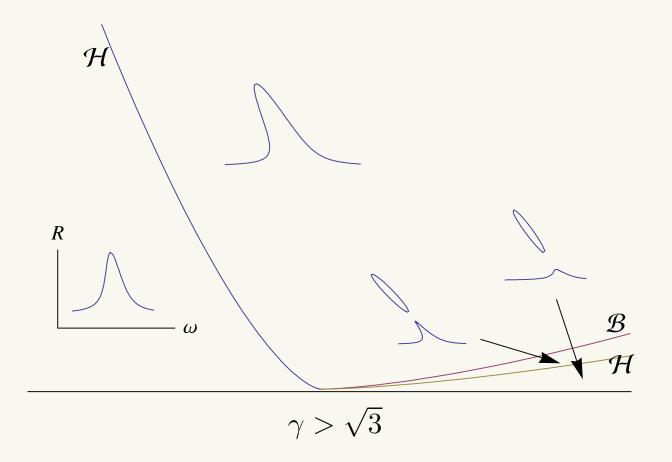
For fixed ε and λ and bifurcation parameter ω , the bifurcation diagrams are



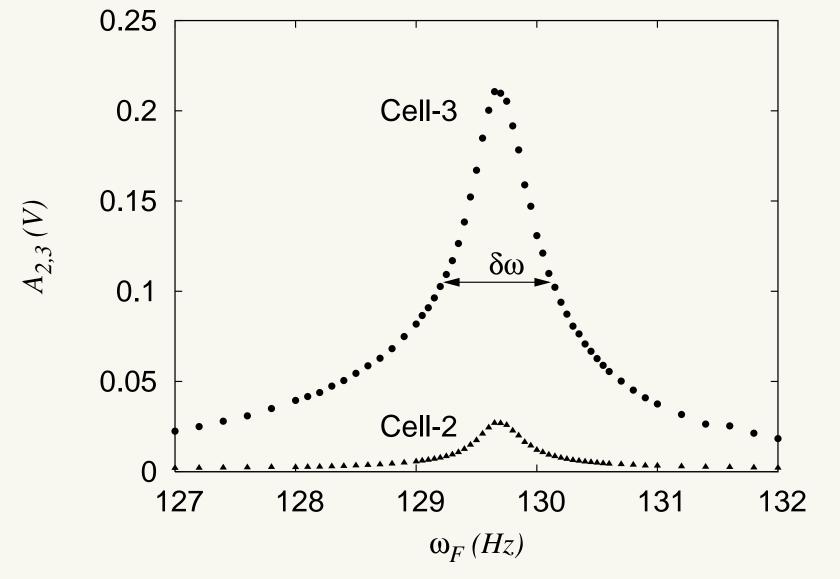
Zhang and G. (2011)

Bifurcation Diagrams: $\gamma > \sqrt{3}$

For fixed ε and λ and bifurcation parameter ω , the bifurcation diagrams are



McCullen-Mullin Experiment



McCullen, Mullin, and G. (2007)

 Γ acts on \mathbf{R}^3 generated by

$$\begin{array}{rccc} (x,y,z) & \mapsto & (\pm x,\pm y,\pm z) \\ (x,y,z) & \mapsto & (y,z,x) \end{array}$$

 $|\Gamma|=24$ and $\Gamma=$ symmetry group of cube

- F(0,0,0) = 0 since $Fix(-x,-y,-z) = \{0\}$
- Coordinate axes flow-invariant since $Fix(-x, -y, z) = \mathbf{R} \{(0, 0, 1)\}$
- Generic pitchfork bifurcation leads to equilibrium on *z*-axis
- Symmetry: equilibria on *x* and *y*-axes
- Coordinate planes are flow-invariant since $Fix(-x, y, z) = \{(0, y, z)\}$

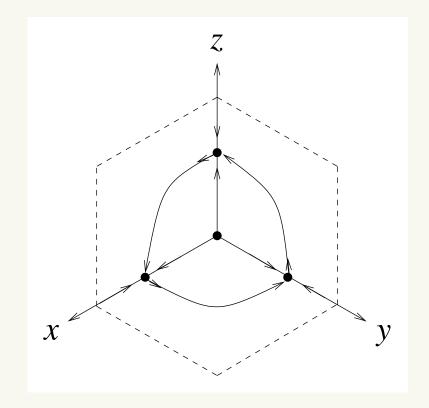
Guckenheimer and Holmes (1988)

Construction of Cycle

Suppose

- There are no other equilibria in coordinate planes
- Two remaining eigenvalues of equilibria on axes have opposite sign
- Infinity is a source

Phase portrait is



Integration of Cycle: $\lambda = 1.0$, A = 1.0, B = 1.5, C = 0.6

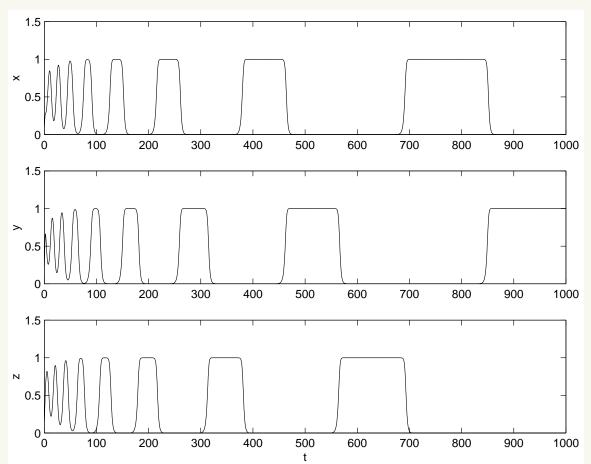
Consider third order truncation of Γ -equivariant system

$$F(x, y, z) = (f_1(x, y, z), f_2(x, y, z), f_3(x, y, z))$$

$$f_1(x, y, z) = \lambda x + (Ax^2 + By^2 + Cz^2)x$$

$$f_2(x, y, z) = \lambda y + (Cx^2 + Ay^2 + Bz^2)y$$

$$f_3(x, y, z) = \lambda z + (Bx^2 + Cy^2 + Az^2)z$$



Breaking Symmetry of Guckenheimer-Holmes Heteroclinic Cycle

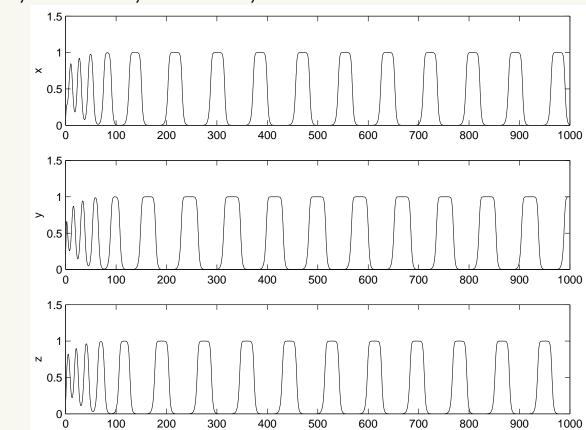
Breaking symmetry perturbs cycle to periodic solution. For example:

$$\dot{x} = x - (Ax^2 + By^2 + Cz^2)x + \epsilon y$$

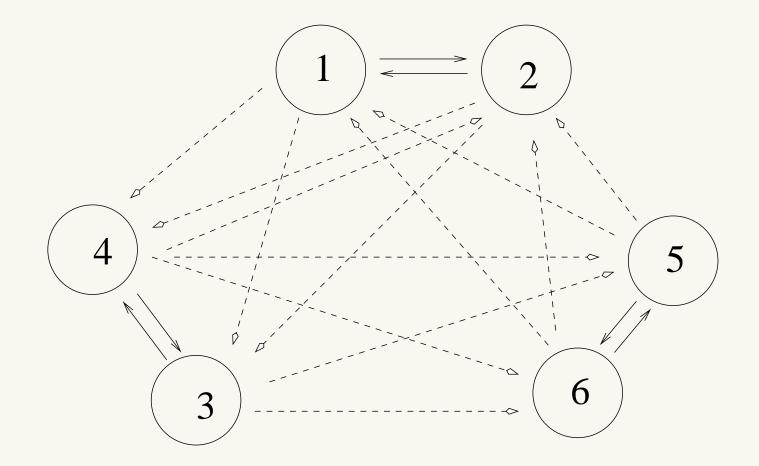
$$\dot{y} = y - (Cx^2 + Ay^2 + Bz^2)y + \epsilon x$$

$$\dot{z} = z - (Bx^2 + Cy^2 + Az^2)z + \epsilon z$$

where $A = 1.0, B = 1.5, C = 0.6, \epsilon = 0.00001$

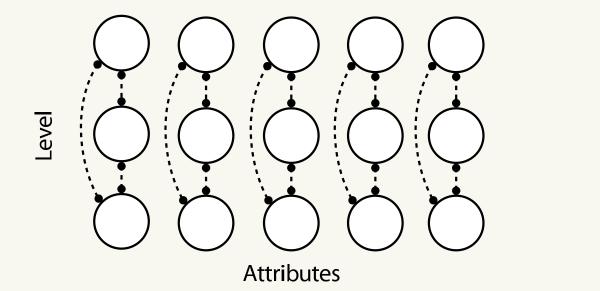


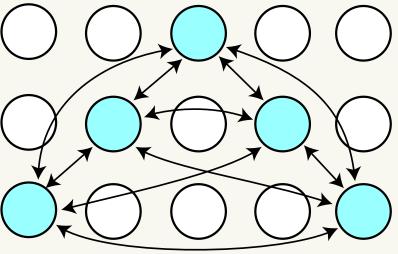
Coupled Cell Version of Guckenheimer-Holmes Cycle



Dionne, G. and Stewart (1994, 1996); Field et al. (2006-12)

Wilson's Generalized Rivalry Model





- Column represent attributes; rows represent level of attribute
- (L) Dashed lines: reciprocal inhibition between cells in column
- (R) Solid lines: reciprocal excitation between cells in learned pattern

Wilson (2008, 2009); Diekman, G., McMillen, and Wang (2012)

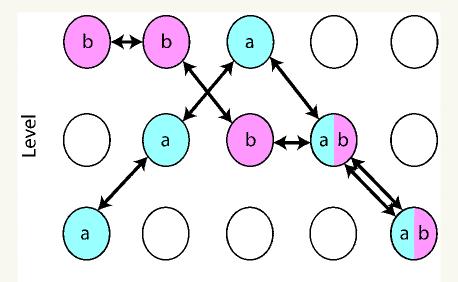
Simplest Rivalry Equations Between Competing Units *a* and *b*

- Units represent perception of images presented to eyes
- Unit a consists of an activity variable a^E representing a firing rate, and a fatigue variable a^H that reduces activity on long time scale

$$\begin{aligned} \varepsilon \dot{a}^E &= -a^E + \mathcal{G} \left(I - \beta b^E - g a^H \right) \\ \dot{a}^H &= a^E - a^H \\ \varepsilon \dot{b}^E &= -b^E + \mathcal{G} \left(I - \beta a^E - g b^H \right) \\ \dot{b}^H &= b^E - b^H \end{aligned}$$

- β is reciprocal inhibition between units
- *I* is external signal strength to units
- a^H reduces the activity in unit a with strength g
- \mathcal{G} is gain: nonnegative, nondecreasing, and $\mathcal{G}(z) = 0$ for $z \leq 0$
- $\varepsilon \ll 1$ is ratio of time scales on which $*^E$ and $*^H$ evolve

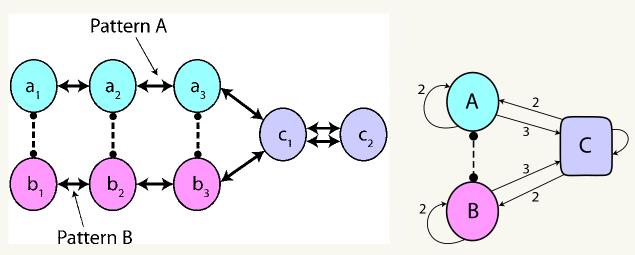
Two Learned Patterns *a* **and** *b*



Attributes

- Network: n attribute columns with m cells representing attribute levels; two equations in each cell
- Learned pattern = one cell from each attribute column
- Reciprocal excitatory connections between these cells
- Cells in learned pattern are all-to-all connected (not indicated)
- Inhibitory connections in columns not indicated

Inactive Cells

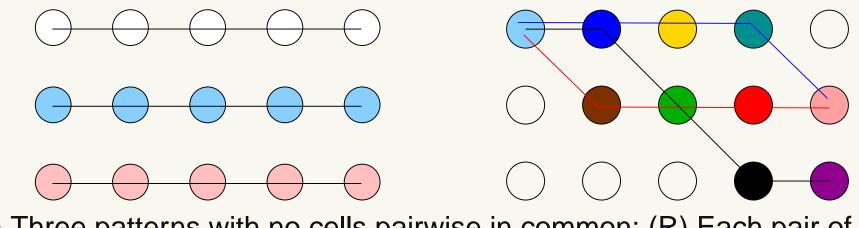


(L) Two learned patterns with 2 cells in common (inactive cells deleted).(R) Quotient network. Integers indicate multi-arrow couplings

- Inactive cells may be ignored, thus reducing network to 2n k cells, where k is number of active cells in common in two-patterns
- Understand dynamics using quotient network: 2-cell network if no cells in common or 3-cell network if cells in common
- Quotient network corresponds to subspace Δ . For many parameters Δ is locally attracting. So, reduction to quotient captures dynamics

Three types of states:

- Fusion = equilibria in which patterns have equal values
- Winner-Take-All = equilibria with different activity levels
- Rivalry = two or more patterns oscillate in periods of dominance
- States: synchronous equilibria; asynchronous equilibria; oscillations
- Rivalry could stem from Hopf bifurcation or heteroclinic cycle



(L) Three patterns with no cells pairwise in common; (R) Each pair of patterns has common active cells

- Wilson: Rivalry predominates in 5 attribute 3 intensity level system when there are four or five learned patterns
- *n* attribute *m* intensity level system can learn *mⁿ* patterns (243 in working example)
- Extreme case (all learned patterns) may be tractable: wreath product $S_m \wr S_n$ with $(m!)^n n!$ elements (933120 in working example)
- Wreath product symmetric coupled systems can lead to heteroclinic cycles. Guckenheimer-Holmes cycle has wreath product group